# Science and Technology English II Exercise 211 "Paper1" Meiji University 2020

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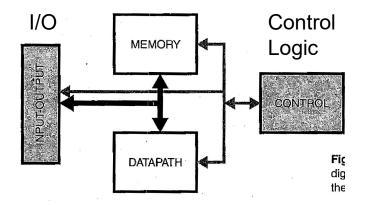
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## Renji Mikami

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# Day 210 Review

- 計算機 (Computer) を考えるポイント
- ・計算機の基本 チューリングマシン-ノイマン型コンピュータ
  - Instruction Flow Sequential (<->Not Dataflow)
- MPUの構成要素
  - Memory, Data Path, Control Logic, I/O
- ・計算機ハードの高速化
  - Path Delay Minimization
    - 信号経路の遅延時間の削減
  - Clock Up
    - 動作速度の高速化
  - Pipeline
    - ・ 演算回路の多段化による並行処理

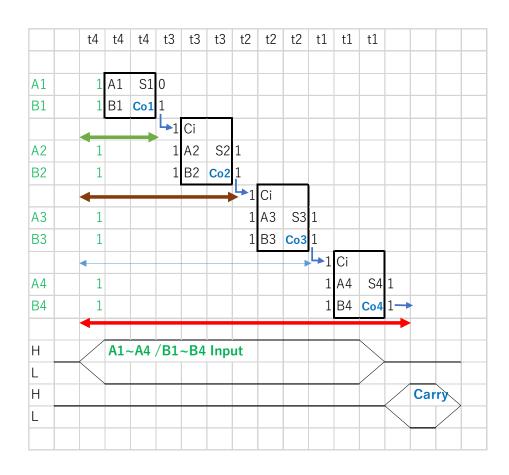


## Day 203-210 Review

- 計算機の高速化:回路は、Data Pass, Control Logic, Grew Logic な どのタイプに分けられる
- Data Path の高速化は、Pipeline 化で行われる
  - シングルサイクル・パスとマルチサイクル・パス-レイテンシ
    - レイテンシ-結果が出てくるまでのクロック数
  - 乱れるパイプライン-パイプライン・ハザード
    - ・ コントロールロジックで制御(1クロックで動作する点に注意)
  - 乱れないパイプライン(垂れ流しパイプライン)-DSPなど
    - Digital Signal Processing (係数の掛け算とその連続した加算を続けることが多い)
- シングルサイクル単位の高速化
  - クリティカル・パスを改善してシステムクロックを最大化する
  - ・システムクロックの最大速度は、クリティカル・パス遅延に制約される
- AdderのCarry生成をクリティカル・パスの典型として扱った

### 4Adder

- A1~A4, B1~B4 **の**4bit 入力
- LSB (A1,B1) のSUM(S1)、 CarryOut(Co1) は 1 Stageで出力される。
- (A2,B2) のSUM(S2)は1 Stage だが、 CarryOut(Co2) は 桁上げを待つので、 2 Stageで出力される。
- (A4,B4) のCarryOut(Co4) は繰り上がりの桁上げを(Ripple Carry)待つので、4 Stageで出力される
- このCarry Line はクリティカル・パスに なりやすいのでいろいろな方法で高 速化される



# Exercise: EX\_211

- 論文の構成法を頭に入れて読みすすめる
- Tech-Term の解説、Tech-Term をWEBで調べる
- ・専門性の高いTech-Term は、その詳細を理解する必要はない。どこで使われるものか、概要だけでよい。
- ・課題論文を要約して和文でまとめてみてください。(翻訳サイトを使ってもよいが、その前に必ず英文を通読すること。)図版や正確なギリシャ文字,数式は配布資料原本を参照のこと。
- 提出はClass Web Report水曜まで

#### Paper1: Wireless Capsule Endoscopic System

# A Wireless Capsule Endoscopic System with a Low-Power Controlling and Processing ASIC

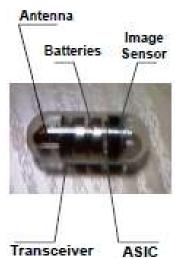
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EX\_211(1): A Wireless Capsule Endoscopic System with a Low-Power Controlling and Processing ASIC (カプセル薬形状の"飲み込む"内視鏡で撮影した写真を無線で伝送する。この装置のASIC設計)

• Abstract—This paper presents the design of a wireless capsule endoscopic system with a low-power controlling and processing ASIC. The ASIC aims at several design challenges including system power reduction, system miniaturization and wireless wake-up method. These challenges are met by deploying optimized system architecture, integration of an area and power efficient image compression module, a power management unit (PMU) and a novel wireless wake-up subsystem with zero standby current. The ASIC has been fabricated in 0.18-μm CMOS technology. The achieved performance will be demonstrated with corresponding measurement results. The wireless capsule endoscope prototype base on the ASIC is under development and the demo system will be brought forth soon.



# EX\_211(2): **まとめを先に、その詳細を各**Sectionで展開することを先述する

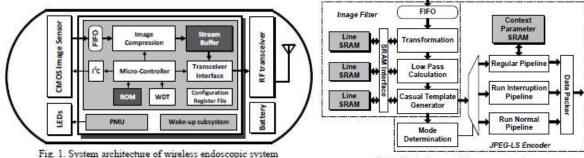
#### I. INTRODUCTION

- Successive improvements in microelectronics and integration technology have led to the emergence of wireless capsule endoscopic systems [1] which can allow people to study the entire small intestine directly. However, several design challenges still have to be tackled. First, the power budget is limited by the battery. Effective low power techniques have to be employed to ensure long lifetime of the system. Second, as few off-chip components as possible are required for highly-miniature-sized system. Third, an untouched wake-up means has to be adopted to turn on/off the system after being hermetically encapsulated within the package. In this paper, a wireless endoscopic system with a controlling and processing ASIC is presented, for which the aforementioned challenges were effectively managed.
- The paper is organized as follows. <u>Section II presents the wireless capsule endoscopic system architecture</u>. <u>Section III gives the design of the ASIC in detail</u>. <u>Section IV describes the implementation and test results</u>. <u>The conclusion is summarized in section V.</u>

#### EX\_211(3): II. DESIGN OF WIRELESS CAPSULE ENDOSCPIC SYSTEM

- The proposed wireless capsule endoscopic system is composed of a digital-analog mix mode ASIC together with a commercial CMOS image sensor and an ultra-low-power RF transceiver, as shown in Fig. 1. The image sensor provides images with VGA resolution at 30fps. The image data would be processed by the ASIC which is composed of a digital baseband processing unit, a power management unit (PMU) and a wireless wake-up subsystem. The ASIC also controls a 433MHz RF transceiver which features with FSK modulation, 200kbps raw data rate and only 5mA current consumption in continuous TX/RX mode. The system is powered by two 1.5V lithium batteries connected in series except the wireless powered wake-up subsystem.
- Once the system is activated by the wake-up subsystem, the integrated PMU has to not only supply on-chip functional blocks but also deliver the power for CMOS image sensor, RF transceiver and illumination LEDs. The clock is also provided by the on-chip oscillator in PMU. Bidirectional communication protocol implemented in the program ROM facilitates the control of the capsule such as changing image size or system status. Image compression is also introduced to reduce both the overall power dissipation and the transmission bandwidth. The compressed data would be received by the data recorder. Finally, the received data would be decompressed and displayed on PC.

#### EX 211(4) III.DESIGN OF LOW-POWER CONTROLLING & PROCESSING IC



- A. System Architecture of the ASIC

Fig. 2. Block diagram of image compression

- One of the primary design targets of battery-operated medical device is power reduction. Measurement result shows that a great fraction of the battery current is consumed by the RF transceiver of which the power dissipation is difficult to optimize. Instead, an architecture level low-power technique, image compression, is introduced in the baseband processing unit to reduce the data mount and associated RF energy. Though image compression itself would cause extra power consumption, is introduced in the baseband processing unit to reduce the data mount and associated RF energy.
- Though image compression itself would cause extra power consumption, compared to the saved RF energy, the overall power reduction can be achieved.
- Unlike the previous architecture based on FSM [2], the proposed architecture is mainly composed of a microcontroller and hardware accelerators. The micro-controller is dedicated to run software that implements high-level communication protocol and flow control. Low-level physical computation is efficiently done by specific hardware accelerator which is better in terms of power consumption and processing time.

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• Unlike the previous architecture based on FSM [2], the proposed architecture is mainly composed of a micro-controller and hardware accelerators. The micro-controller is dedicated to run software that implements high-level communication protocol and flow control. Low-level physical computation is efficiently done by specific hardware accelerator which is better in terms of power consumption and processing time.

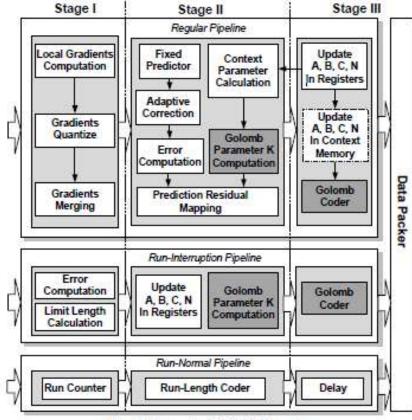


Fig. 3. Data path of JPEG-LS encoder

#### EX\_211(6): B. Area and Power Efficient Image Compression module

• The integrated image compression module is dedicated developed for Bayer color filter array (CFA) pattern of CMOS image sensor with great concern of area and power efficiency. The block diagram is shown in Fig. 2. It is mainly composed of an image filter and a standard JPEG-LS encoder [3]. The VLSI-oriented image filter algorithm derived from [4] acts as a preprocessing step for JPEG-LS encoder. It performs pixel transformation and low-pass filtering calculation to depress the high spatial frequencies so as to promote the compression ratio of the following JPEG-LS encoder. JPEG-LS is an established standard for lossless compression, which provides both the highest lossless compression ratio and the fastest compression speed for medical images.

#### EX\_211(7):

• To get an area and power efficient VLSI implementation of JPEG-LS encoder, the data path has been optimized for minimum resource utilization and power consumption. Three parallel three-stage pipelines are designed separately for regular mode, run interruption state and run normal state, as shown in Fig. 3. Each stage is allocated with four clock cycles. For each pixel, only one pipeline is activated by the mode determination unit, which avoids the unnecessary computation of the other two pipelines and leads to considerable power reduction. Experiment has shown that independent data path for different modes and states can cause an average of 45% power reduction, especially for flat images, because most pixels will be processed by Run-Normal pipeline with very simple computation. In addition, in-stage resource sharing is extremely exploited between pipelines for common computation such as Golomb parameter k in the second stage and Golomb coder in the third stage, as shown in the dark gray color in Fig. 3.

#### EX\_211(8):

- A two-level hierarchy memory access method is proposed to eliminate unnecessary memory accesses in the process of context parameters (A, B, C, N) updating. In the proposed method, the context parameters are firstly cached in registers in Regular pipeline. The context memory will be accessed only if the next pixel belongs to a different context model, otherwise the value of registers will be used for accumulation without memory access, as shown in Fig.4.
- Hence the update of context memory only activates when the quantized context changes which cause an average of 52% reduction of the number of memory access. This results in obvious reduction of associated power dissipation.

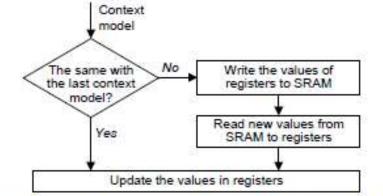


Fig. 4. Memory accesses reduction method of JPEG-LS encoder

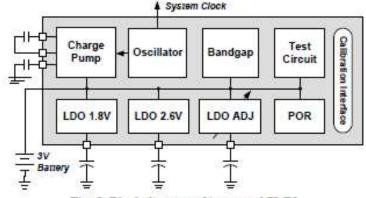
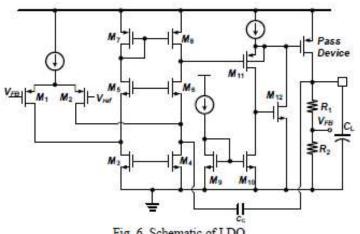


Fig. 5. Block diagram of integrated PMU

#### EX 211(9): C. Power Management Unit (PMU)

- The miniature size requirement of wireless endoscopic system makes very severe demand on the area of PCB board as well as the number of on-board components. The integration of PMU allows one to reduce the onboard components and PCB routing area. The block diagram of PMU is shown in Fig. 5.
- The 3.3 maximum operating voltage of the 0.18-μm CMOS technology facilitates the design of LDO which regulates the battery voltage 3V down to a desired output voltage. The LDO can be directly powered by battery without over-voltage problem. Fig. 6 illustrates the LDO circuitry design derided from [5]. It is composed of an error amplifier (M1~M8), a unit-gain buffer (M9~M12), a PMOS pass device, a feedback network (R1, R2) and off-chip loading capacitance CL.



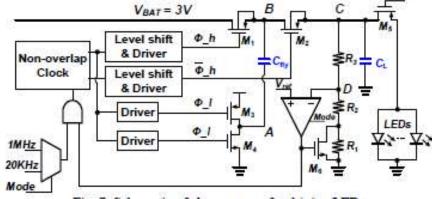


Fig. 6. Schematic of LDO

Fig. 7. Schematic of charge pump for driving LEDs

#### EX\_211(10):

- Illumination LEDs need a constant voltage higher than the battery voltage to provide constant light density. This is achieved by the integrated charge pump, as shown in Fig. 7.
- M1, M4, M2, M3 and the off-chip capacitances Cfly, CL form a voltage doubler which could generate twice of VBAT at node C. A comparator is used for regulating the output voltage to a desired value. To save the energy, two different operating modes are implemented. When strobe signal is active, the charge pump works in high speed mode with high clock frequency and bias current, which results in large output current sourcing ability. Otherwise, low clock frequency and bias current are employed to sustain the output voltage.
- The clock of charge pump and the digital core is generated by a fully integrated on-chip oscillator. The reference voltage is generated by bandgap reference.

#### EX\_211(11): D. Wireless wake-up subsystem RFID CDR keying

- A RFID-like wireless wake-up subsystem is integrated to replace the conventional dry reed switch. It can wirelessly enable/disable the system or to make a configuration of the system after being hermetically encapsulated within the package.
- The function blocks in the wake-up subsystem are shown in Fig. 8. The energy recovery block converts part of the incoming RF signal power to a dc voltage (VRF) which supplies all active circuits. The clock and data recovery (CDR) block recovers a digital signal from the received RF signal with amplitude shift keying (ASK) modulation, and generates a synchronous clock signal. The identification and command recognition (ICR) block compares the received device identification code with the desired value and then recognizes valid switching command. After that, the ICR block generates enable/disable signal through level shifter to the PMU. Therefore, the wireless endoscopic system can be wireless enabled/disabled without extra power consumption.

#### EX\_211(12): IV. IMPLEMENTATION RESULTS

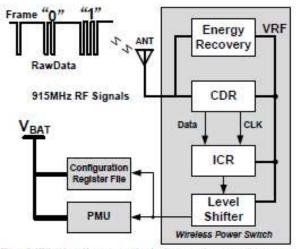
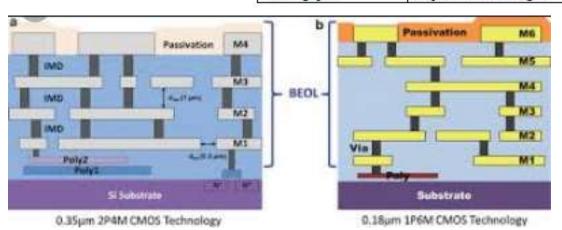


Fig. 8. Blocks diagram of wireless wake-up subsystem

Technology	0.18-μm 1P6M CMOS		
Die size	3.4 mm x 3.3 mm		
Supply voltage	3 V		
Off-chip components	5 capacitances less than 1μF		
Logic gates	23.4 k		
Memory	764 kbits (10.2k for image filter, 17.5k for JPEG-LS encoder, 737k for stream buffer)		

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Clock frequency	20~24MHz (Adjustable)	
Image resolution	VGA or QVGA	
Compression ratio	3 ~ 4 bpp	
Throughput	2 fps for VGA images	



• The digital-analog mix mode ASIC has been fabricated in 0.18-µm 1P6M CMOS technology. The chip layout is shown in Fig. 9 and chip performance is summarized in Table I.

#### EX\_211(13): LDO Low Dropout (DC-DC) Regulator JPEG-LSは調べてみよう

- Table II shows a comparison of the proposed implementation of JPEG-LS encoder (without image filter) to other implementations available in academia. It is easily observed that the proposed JPEG-LS implementation presents the lowest gate counts (19.5k) and the lowest memory requirements (17.5kbits).
- The design specifications of the LDO's and the charge pump are shown in table III and table IV, respectively. The start-up waveform of LDOs and charge pump from a previous version implementation is shown in Fig.10.

TABLE II	Comparisons with the other JPEG-LS encoder
	implementations

impiementations						
	[6]	[7]	[8]	[8]	This work	
Year	2005	2002	2007	2007	2008	
Technology (um)	UMC 0.18	unknow n	TSMC 0.18	TSMC 0.09	UMC 0.18	
Resolution (pixels/ line)	640	640	640	640	640	
Logic Gates	70 k	49.4 k	28.1 k	25.7 k	19.5 k	
Memory (bits)	24 k	32.7 k	20.8 k	20.8 k	17.5 k	

TABLE III.	PERFORMANCE SUMMARY OF LDOS			
	1.8V & 1.1V LDO	2.6V LDO	Condition	
Vin	3.0V	3.0V	,	
Load Capacitance	1μF	1μF		
Output current	0~30mA	0~30mA		
Quiescent current	18µA	20μA	No load current	
Line regulation	0.25mV	0.14mV	Vin 2.8V~3.2V	
Load regulation	1.9mV	2.0mV	I <sub>Load</sub> 0.1~30mA	
Power Supply Rejection	73dB	72dB	Frequency @50kHz	
Chip area	0.046mm <sup>2</sup>	$0.046 \text{mm}^2$		

#### EX\_211(14): charge pump は調べてみよう LDOとの違いは?

- The measurement from a separate prototype IC shows that wireless wake-up subsystem can supply at least 2.7  $\mu$ A current to an external load when received a RF power as low as 60  $\mu$ W. 25 kbps data rate can be achieved when receiving commands. The standby current of WWU is always below 10 nA.
- A system prototype based on the proposed ASIC is being developed, of which the photo is shown in the right of Fig. 9. The system is encapsulated in the package with the size of Φ11.3mm, length 26.7mm.

TABLE IV. PERFORMANCE SUMMARY OF CHARGE PUMP

Mode	Clock	Icontrol	Vout	Voltage Ripple
High speed	1MHz	14μA	4V	50mV@5mA
Low speed	20KHz	4μΑ	4V	210mV@0mA
Standby	No clk	< 1nA	0V	100

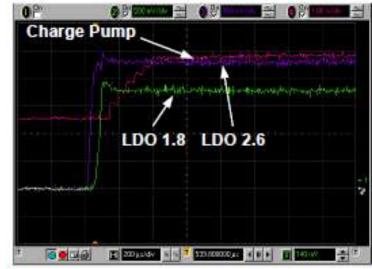


Fig. 10. Start-Up waveforms of LDOs and charge pump (the other blocks are not shown)

#### EX\_211(15) : V. CONLUSION

• This paper presented a wireless endoscopic system with a controlling and processing ASIC, which is composed of a digital baseband module with image compression ability, an integrated power management unit and a wireless wake-up subsystem. The ASIC has been fabricated in 0.18um CMOS technology and a system prototype has been developed on it. Experiment result shows that the ASIC eases the implementation of a low-power miniaturized wireless capsule endoscopic system.

#### EX\_211(16): REFERENCES

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#### Memo

フォローアップURL (Revised)

http://mikami.a.la9.jp/meiji/MEIJI.htm

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